

§ Diagonalizability.

Recall: Matrix A is called diagonalizable if A is similar to a diagonal matrix.

i.e., \exists invertible matrix Q , s.t. $Q^{-1}AQ$ is $\begin{pmatrix} \lambda & & \\ & \ddots & \\ & & \lambda \end{pmatrix}$.

Question: Is every matrix diagonalizable?

Answer:

No !!!

e.g. $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix}$

Def: Suppose $T \in L(V)$. V finite-dim.

Then T is **diagonalizable** if one of the following equivalent conditions is true.

(1) (Vector Space form) V has an ordered basis β in which each basis vector is an eigenvector of T .

(2) (Matrix Form) V has an ordered basis β s.t. $[T]_{\beta}$ is diagonal.

pf of equivalence: Suppose $\beta = \{\vec{v}_1, \dots, \vec{v}_n\}$

$$T(\vec{v}_j) = \lambda_j \cdot \vec{v}_j \quad \Leftrightarrow \quad [T]_{\beta} = \begin{pmatrix} \lambda_1 & 0 & & \\ 0 & \lambda_2 & & \\ \vdots & \vdots & \ddots & \\ 0 & 0 & & \lambda_n \end{pmatrix}$$

Note: NOT all linear operators are diagonalizable:


e.g. T rotation (by 90°) on \mathbb{R}^2 .

We know T has no eigenvalue & eigenvector.

Use Vector Space Form of diagonalizability $\Rightarrow T$ is not diag.

Consequently, not all matrices are diagonalizable!

e.g. $[T]_\beta = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ is not diagonalizable.

 Question: When is T diagonalizable?

(1) Simple Criterion • in terms of characteristic polynomial $f_T(t)$ only.

• normal operator *Latev ...*

(2) General Necessary & Sufficient Condition

(involves additional data than char poly - harder to check!)

Def: A poly $f(t) \in P(F)$ splits over F if $\exists c$ & $\underbrace{a_1, \dots, a_n}_{\text{(not necessarily distinct)}}$ $\in F$
s.t. $f(t) = c(t - a_1) \dots (t - a_n)$, i.e., has n roots.

Ex: - If $F = \mathbb{R}$. Not all $f \in P(\mathbb{R})$ can split over \mathbb{R} , e.g. $f(t) = t^2 + 1$

· If $F = \mathbb{C}$, then any $f \in P(\mathbb{C})$ splits over \mathbb{C} (by Fund Thm of Alg.)

Theorem: The characteristic poly of a diagonalizable linear operator
(Necessary condition)
on a finite-dim space V splits over F .

pf: If V is n -dim and $T \in \mathcal{L}(V)$ is diagonalizable.

Then \exists a basis $\beta \subset V$. s.t. $[T]_{\beta} = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$

$$\begin{aligned} \text{Then. } f_T(t) &= \det([T]_{\beta} - tI_n) \\ &= (-1)^n (t - \lambda_1) \cdots (t - \lambda_n) \end{aligned} = \begin{pmatrix} \lambda_1 - t & & 0 \\ & \lambda_2 - t & \\ 0 & & \ddots \\ & & & \lambda_n - t \end{pmatrix}$$

□

~~Theorem.~~ Theorem. Let $T \in \mathcal{L}(V)$ with $\dim V = n$.
(Sufficient cond.)

If T has n distinct eigenvalues, then T is diagonalizable.

Pf: Let $\lambda_1, \dots, \lambda_n$ are n distinct eigenvalues of T .

For each λ_i , let \vec{v}_i be the associated eigenvectors
Define $\beta = \{ \vec{v}_1, \dots, \vec{v}_n \}$

Claim. β is linearly indep. (pf below).

$\Rightarrow \beta$ is a basis for V . $\Rightarrow T$ is diagonalizable \square

Lemma: A set of eigenvectors associated to distinct eigenvalues of T are linearly indep.

Df: Induction on $k := \#$ of vectors.

• $k=1$. $\{\vec{v}_1\}$ ^{$\neq \vec{0}$} eigenvector is lin. indep.

• Assume true for k vectors $\{\vec{v}_1, \dots, \vec{v}_k\}$. Add the vector \vec{v}_{k+1} .

Let $S = \{\vec{v}_1, \dots, \vec{v}_{k+1}\}$ where $T(\vec{v}_i) = \lambda_i \vec{v}_i$ and $\lambda_1, \dots, \lambda_{k+1}$ distinct.

To show S lin. indep. let $\sum_{i=1}^{k+1} a_i \vec{v}_i = \vec{0}$. (1)

Apply linear operator T : $T\left(\sum_{i=1}^{k+1} a_i \vec{v}_i\right) = 0$

$$\Rightarrow \sum_{i=1}^{k+1} a_i \lambda_i \vec{v}_i = 0 \quad (2)$$

$$(2) - \lambda_{k+1} \cdot (1): \quad \sum_{i=1}^k a_i (\lambda_i - \lambda_{k+1}) \vec{v}_i = 0$$

By inductive hyp, $\{\vec{v}_1, \dots, \vec{v}_k\}$ lin. indep $\Rightarrow a_i (\lambda_i - \lambda_{k+1}) = 0$
 $\neq 0$

Since $\lambda_1, \dots, \lambda_k$ distinct $\Rightarrow \lambda_i - \lambda_k \neq 0 \Rightarrow a_1 = \dots = a_k = 0$.

(1) $\Rightarrow a_{k+1} \vec{v}_{k+1} \neq 0 \Rightarrow a_{k+1} = 0$; hence $\{\vec{v}_1, \dots, \vec{v}_{k+1}\}$ lin. indep. \square

Summary

- Necessary Condition : If T is diagonalizable, then $f_T(t)$ must split. i.e., $f_T(t) = c(t-a_1)\dots(t-a_n)$
- Sufficient Condition : If $f_T(t)$ has n distinct roots. i.e., a_1, \dots, a_n are distinct then T is diagonalizable

Example: $T = L_A: \mathbb{F}^2 \rightarrow \mathbb{F}^2$. $A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$

Char poly: $f_T(t) = t^2 + 1$

← geometrically rotation.

• When $\mathbb{F} = \mathbb{R}$. $f_T(t)$ does not split $\Rightarrow T$ is NOT diagonalizable.

• When $\mathbb{F} = \mathbb{C}$ $f_T(t) = (t+i)(t-i)$, 2 distinct roots $\Rightarrow T$ is diagonalizable.

Indeed, $T \begin{pmatrix} 1 \\ -i \end{pmatrix} = \underline{i} \begin{pmatrix} 1 \\ -i \end{pmatrix}$ $T \cdot \begin{pmatrix} 1 \\ i \end{pmatrix} = \underline{-i} \begin{pmatrix} 1 \\ i \end{pmatrix}$

$\Rightarrow \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} = Q^{-1} \cdot \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \cdot Q$, where $Q = \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix}$. $Q^{-1} = \frac{1}{2} \begin{pmatrix} 1 & i \\ 1 & -i \end{pmatrix}$

Def: Let λ be an eigenvalue of $T \in \mathcal{L}(V)$ with char poly $f_T(t)$.

The algebraic multiplicity of λ , denoted $m_T(\lambda)$,

is the multiplicity of λ as a zero of $f(t)$
i.e., the largest k , s.t. $(t-\lambda)^k \mid f_T(t)$

Note: When char. poly $f_T(t)$ splits, write $f_T(t) = c(t-\lambda_1)^{m_1}(t-\lambda_2)^{m_2}\cdots(t-\lambda_k)^{m_k}$

Then $m_i =$ algebraic multiplicity of λ_i . $\lambda_1, \dots, \lambda_k$ distinct

Also, $m_1 + \dots + m_k = n = \dim V$.

Example : \bullet 1 is an eigenvalue of $I_V: V \rightarrow V$.

With $\mu_{I_V}(1) = \dim V$.

$$\begin{pmatrix} 1-t & & \\ & \ddots & \\ & & 1-t \end{pmatrix}$$
$$f_{I_V}(t) = (1-t)^n$$

\bullet For $A = \begin{pmatrix} 3-t & 1 & 0 \\ 0 & 3-t & 4 \\ 0 & 0 & 4-t \end{pmatrix}$

$$f_A(t) = (3-t)^2 \cdot (4-t)$$

$$\Rightarrow \mu_A(3) = 2 \quad \mu_A(4) = 1$$

Recall: Eigenspace $E_\lambda := N(T - \lambda I_V) = \{ \vec{x} \in V : T(\vec{x}) = \lambda \vec{x} \}$

Def: $\gamma_T(\lambda) := \dim E_\lambda$. the **geometric multiplicity** of λ .

Prop: Let $T \in L(V)$, V finite-dim space. Let λ be an eigenvalue of T

Then $1 \leq \gamma_T(\lambda) \leq \mu_T(\lambda)$.

pf: • Take a basis $\{ \vec{v}_1, \dots, \vec{v}_p \}$ for E_λ and extend to a basis $\beta = \{ \vec{v}_1, \dots, \vec{v}_p, \vec{v}_{p+1}, \dots, \vec{v}_n \}$ for V .

$$\text{Then } [T]_\beta = \left(\begin{array}{cccc|cc} \lambda & 0 & \dots & 0 & * & * \\ 0 & \lambda & & \vdots & & \\ \vdots & 0 & & \dots & * & * \\ \vdots & & & \lambda & & \\ \vdots & & & 0 & & \\ 0 & 0 & \dots & 0 & * & * \end{array} \right) = \left(\begin{array}{c|c} \lambda I_p & B \\ \hline 0 & C \end{array} \right) \quad - t I_n$$

$$\Rightarrow f_T(t) = \det \left(\begin{array}{c|c} (A-t)I_p & B \\ \hline 0 & C-tI_{n-p} \end{array} \right)$$

$$= (A-t)^p \cdot \det(C-tI_{n-p})$$

$$\text{So } \mu_T(\lambda) \geq p = \nu_T(\lambda)$$

- On the other hand, λ eigenvalue $\Leftrightarrow T - \lambda I_V$ is not invertible
 $\Leftrightarrow N(T - \lambda I_V) = E_\lambda$ has $\dim \geq 1$

Hence, $1 \leq \nu_T(\lambda)$.

□

~~★~~ Theorem: (Sufficient & Necessary Conditions for diagonalizability)

Suppose $T \in L(V)$. s.t. the char poly $f_T(t)$ splits. $\mu_T(\lambda_1) + \dots + \mu_T(\lambda_k) = n = \dim V$

Let $\lambda_1, \dots, \lambda_k$ be the distinct eigenvalues of T .

Then:

$$\Rightarrow \gamma_T(\lambda_1) + \dots + \gamma_T(\lambda_k) = n$$

(a) (test) T is diagonalizable iff $\mu_T(\lambda_i) = \gamma_T(\lambda_i) \quad \forall i=1, \dots, k$.

(b). If T is diagonalizable and β_i is a basis for $E_{\lambda_i} \quad \forall i$.
(explicit basis) then $\beta := \beta_1 \cup \dots \cup \beta_k$ is a basis for V .
Consisting of eigenvectors of T (so that $LT|_{\beta}$ is diagonal)

Example

(1) For $A = \begin{pmatrix} 3 & 1 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{pmatrix}$ $\chi_A(t) = (3-t)^2 \cdot (4-t)$. splits over \mathbb{R} .

$$\mu_A(3) = 2 \quad \mu_A(4) = 1.$$

• Since $1 \leq \gamma_A(4) \leq \mu_A(4) \Rightarrow \gamma_A(4) = 1 = \mu_A(4)$.

• How about $\gamma_A(3)$?

$$E_3 = \mathcal{N}(A - 3I) = \mathcal{N} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \Rightarrow \gamma_A(3) = 1 < \mu_A(3)$$

$$= \left\{ c \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\} \quad 1\text{-dim.} \Rightarrow A \text{ is not diagonalizable.}$$

(2). Consider $T: P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ defined by

$$f(x) \mapsto f(1) + f'(0) \cdot x + (f'(0) + f''(0)) \cdot x^2$$

Let α be the standard basis for $P_2(\mathbb{R})$. $\alpha = \{1, x, x^2\}$

Then $[T]_{\alpha} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix}$

$$1 \mapsto 1$$

$$x \mapsto 1 + x + x^2$$

$$x^2 \mapsto 1 + 0 \cdot x + 2x^2$$

$\Rightarrow f_T(t) = (1-t)^2 \cdot (2-t)$ Splits over \mathbb{R} .

And the eigenvalues of T are 1 and 2

$$\mu_T(1) = 2$$

$$\mu_T(2) = 1$$

Then determine the geometric mult:

- We have $\chi_T(2) = 1 = \eta_T(2)$

- Note that $[T - 1 \cdot I_V]_{\alpha} = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix} \Rightarrow \text{rank} = 1$

$$\Rightarrow \chi_T(1) = \dim N(T - I_V) = 2 = \eta_T(1)$$

So T is diagonalizable

Indeed, for $[T]_\alpha$, the eigenspaces are.

$$E_1 = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 : x_2 + x_3 = 0 \right\}, \text{ so } \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\} \text{ is a basis.}$$


$$E_2 = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 : x_2 = -x_1 + x_2 + x_3 = 0 \right\}, \text{ so } \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\} \text{ is a basis.}$$

$$\Rightarrow \gamma = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\} \text{ is a basis for } \mathbb{R}^3 \text{ consisting of eigenvectors of } [T]_\alpha$$

and it corresponds to the basis $\beta = \{1, x - x^2, 1 + x^2\}$ eigenvectors of T .

□

Lemma: Suppose $T: V \rightarrow V$ has distinct eigenvalues $\lambda_1, \dots, \lambda_k$.

 For each $i=1, \dots, k$, let $S_i \subseteq E_{\lambda_i}$ be a finite lin. indep subset

Then $S = S_1 \cup S_2 \cup \dots \cup S_k$ is a linearly indep subset of V .

Recall: "A set of eigenvectors associated to distinct eigenvalues of T
are linearly indep." (*)

pf: Suppose $S_1 = \{ \vec{v}_{11}, \vec{v}_{12} \dots \vec{v}_{1n_1} \}$ $\vec{w}_1 = a_{11}\vec{v}_{11} + \dots + a_{1n_1}\vec{v}_{1n_1} \in E_{\lambda_1}$

$S_2 = \{ \vec{v}_{21}, \vec{v}_{22} \dots \vec{v}_{2n_2} \}$ $\vec{w}_2 = a_{21}\vec{v}_{21} + \dots + a_{2n_2}\vec{v}_{2n_2} \in E_{\lambda_2}$

\dots
 $S_k = \{ \vec{v}_{k1}, \vec{v}_{k2} \dots \vec{v}_{kn_k} \}$ $\vec{w}_k = a_{k1}\vec{v}_{k1} + \dots + a_{kn_k}\vec{v}_{kn_k} \in E_{\lambda_k}$

then $S = \{ \vec{v}_{ij} : 1 \leq i \leq k, 1 \leq j \leq n_i \}$

Assume $\sum_{i=1}^k \sum_{j=1}^{n_i} a_{ij} \vec{v}_{ij} = 0$

\vec{w}_i

Let $\vec{w}_i = \sum_{j=1}^{n_i} a_{ij} \vec{v}_{ij} \in E_{\lambda_i}$; Then $\sum_{i=1}^k \vec{w}_i = 0$

Then (*) implies $\vec{w}_i = 0 \quad \forall i$

Hence $\sum_{j=1}^{n_i} a_{ij} \vec{v}_{ij} = 0$. As S_i lin indep, $a_{ij} = 0$

Hence $S = S_1 \cup \dots \cup S_k$ lin. indep.

□

" \Leftarrow ": Assume $\gamma(\lambda_i) = \mu(\lambda_i) \quad \forall i=1, \dots, k$.

Let β_i be a basis for E_{λ_i} . Let $\beta = \beta_1 \cup \dots \cup \beta_k$.

By Lemma, we know β lin. indep.

$$\text{Also } \#\beta = \sum_{i=1}^k \#\beta_i = \sum_{i=1}^k \gamma(\lambda_i) = \sum_{i=1}^k \mu(\lambda_i) = \dim V.$$

Hence β is a basis for V consisting of eigenvectors of T .
 β_i basis *assumption* *char. poly. splits.*

i.e., T is diagonalisable.

□